3D Object Classification via Spherical Projections

Zhangjie Cao¹, Qixing Huang², and Ramani Karthik³

¹School of Software Tsinghua University, China

²Department of Computer Science University of Texas at Austin, USA

³School of Mechanical Engineering Purdue University, USA

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Main-stream Methods

• Two main-stream 3D classification methods: image-based and 3D-based.



 Spherical projections combine key advantages of these two main-stream 3D classification methods.

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Depth-based Projection



Figure: Depth-based Projections and Networks

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Depth-based Projection

Depth-based Projection



Figure: Details on Depth-based Projection

- Depth values are recorded as the distance to the first hitting point
- First compute depth values for vertices of a semi-regular quad-mesh
- Then generate the depth value of other points by linear interpolation.

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Contour-based Projection



Figure: Contour-based Projections and Networks

Experiments Setup

- Datasets: ModelNet40, ShapeNetCore
- Parameter selection: cross-validation by jointly assessing
- Methods to compare with: Image-based methods: MVCNN, MVCNN-MultiRes; 3D-based methods: 3D ShapeNets, Voxnet, Volumetric CNN, OctNet; combined methods: FusionNet. All of these methods use the upright orientation but do not use the front orientation.

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Results

• Accuracy of our approaches and the various baseline methods on ModelNet40 and ShapeNetCore and two curated subsets.

| Method | ModelNet40 | ShapeNetCore | ModelNet40-Subl | ShapeNetCore-SubI |
|-----------------------|------------|--------------|-----------------|-------------------|
| 3D Shapenets | 85.9 | na | 83.33 | na |
| Voxnet | 87.8 | na | 85.99 | na |
| FusionNet | 90.80 | na | 89.54 | na |
| Volumetric CNN | 89.9 | na | 88.65 | na |
| MVCNN | 92.31 | 88.93 | 91.22 | 88.64 |
| MVCNN-MultiRes | 93.8 | 90.01 | 92.60 | 90.00 |
| OctNet | 87.83 | 88.03 | 86.45 | 87.85 |
| depth-base pattern | 91.36 | 89.45 | 90.25 | 89.13 |
| contour-based pattern | 93.31 | 90.49 | 92.20 | 90.80 |
| overall pattern | 94.24 | 91.00 | 93.09 | 91.22 |

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Results

Results

• Accuracy Before and After Pre-training on ModelNet40

| Mathad | Before Pre-training | | After Pre-training | |
|-----------------------|---------------------|---------------------|--------------------|---------------------|
| Method | Accuracy (class) | Accuracy (instance) | Accuracy (class) | Accuracy (instance) |
| MVCNN | 82.15 | 87.15 | 90.35 | 92.31 |
| MVCNN-MultiRes | 88.12 | 91.20 | 91.40 | 93.80 |
| depth-base pattern | 80.44 | 86.09 | 87.32 | 91.36 |
| contour-based pattern | 88.33 | 91.48 | 91.16 | 93.31 |
| overall pattern | 88.53 | 91.77 | 91.56 | 94.24 |

• Accuracy Before and After Pre-training on ShapeNetCore

| Method | Before Pre-training | | After Pre-training | |
|-----------------------|---------------------|---------------------|--------------------|---------------------|
| | Accuracy (class) | Accuracy (instance) | Accuracy (class) | Accuracy (instance) |
| MVCNN | 67.84 | 84.55 | 78.79 | 88.93 |
| MVCNN-MultiRes | 75.34 | 88.4 | 79.01 | 90.01 |
| depth-base pattern | 70.55 | 85.15 | 78.84 | 89.45 |
| contour-based pattern | 74.52 | 88.54 | 79.38 | 90.49 |
| overall pattern | 75.60 | 88.87 | 80.38 | 91.00 |

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Analysis

• Accuracy w.r.t Number of Views for Depth and Contour Pattern on ModelNet40 and ShapeNetCore

| Pattern | Number of Views | ModelNet40 | ShapeNetCore |
|---------------|-----------------|------------|--------------|
| depth-based | 6 | 90.87 | 88.95 |
| | 24 | 91.02 | 89.23 |
| | 12 | 91.36 | 89.45 |
| contour-based | 6 | 92.26 | 89.23 |
| | 24 | 93.12 | 90.36 |
| | 12 | 93.31 | 90.49 |

• Accuracy w.r.t Elevation degree of the strip parallel to the latitude



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Summary

- We introduce a spherical representation exploiting both depth variation and contour information which can capture geometric details and data dependencies across the entire object.
- We develop deep neural networks incorporating large-scale labeled images for training to classify spherical representations of 3D objects.
- In the future, we plan to define convolutional kernels directly on spherical domains.

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